TB6560

3A FULL BRIDGE STEPMOTOR DRIVER

INPUT: 10-35VDC (24 Nominal) **OUTPUT:** Selectable up to 3A max. **STEP:** Full & 1/2-1/8-1/16 Microstep Full bridge driver for 4 or 6 wire hybrid stepmotors. Automatic drop to Hold current with no step Input. Switch Selectable output current. .3A-3A Over temperature & current Protected. Under Voltage Shutdown Opto isolated Step, Direction & Enable Inputs. (+5V Level) Terminal strips in/out. Power and Run LEDs



RUN B-B+ A-A+ GND +24V 뒦 2 SM1 SW2 SM3 S1 S2 **S**3 Ц Optocouplers S4 **S**5 S6 EN+ CW- CW+ CLK- CLK+ EN-Power

Wiring Terminal symbol	Description
+24V, GND	Power positive and negative
A+, A-	Motor phase A
B+, B-	Motor phase B
CLK+, CLK-	Pulse positive and negative
CW+, CW-	Direction positive and negative
EN+, EN-	Enable positive and negative

Warning:

1: Check the connection twice! The6560 chipset can be damaged if the motor or the power supply are not connected properly.

2: Don't connect a motor with a rated current in excess of 3A to this driver.

3: Do not set the current higher than the motor rated current!

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Note:

- **1:** 6 input terminals can be connected as common anode or cathode.
- 2: The normal input voltage is 5V. If more than 5V, then a series resistor **R** is needed For 12V this resistance is 1K, For 24V the resistance is 2.4K..
- 3: When pulses are applied to CP, the motor will rotate. Motor will stop when there is no CP pulse, and the driver will change to a holding current of 50% or 20% of the Running Current & S2 setting
- 4: Motor will rotate clockwise when **CW** is low level and counter clockwise when **CW** is a High level
- 5: Motor is enable when EN is low level and disable when EN is high level.

Running Current							Excitation Mode										
(A)	0.3	0.6	1	1.4	1.9	2.2	2.6	3.0	STEP	NC	1	2	2	4	8	16	32
SW4	ON	OFF	ON	OFF	ON	OFF	ON	OFF	sw1	ON	ON	ON	OFF	ON	OFF	OFF	OFF
SW5	ON	ON	OFF	OFF	ON	ON	OFF	OFF	SW2	ON	ON	OFF	ON	OFF	ON	OFF	OFF
SW6	ON	ON	ON	ON	OFF	OFF	OFF	OFF	SW3	ON	OFF	ON	ON	OFF	OFF	ON	OFF
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